Solve Problem

Multi-Layer Perceptron in MATLAB NN Toolbox

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Multi-Layer Perceptron - part 1

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Training

Introduction

- Rosenblatt in 1961 created many variations of the perceptron
- One of the simplest was a single-layer network whose weights and biases could be trained to produce a correct target vector when presented with the corresponding input vector



Figure: Perceptron Representation-[1]



 There are many transfer function that can be used in the perceptron structure, e.g.



Figure: hardlim, purelin, logsig

Usually hardlim is selected as default

Perceptron Architecture

- The perceptron network consists of a single layer
- R input vector
- S output scaler

Here, we consider just one-layer perceptron



a = hardlim(Wp + b)

Figure: Perceptron Architecture

Mathematical Notation

- A single superscript is used to identify elements of a layer, *e.g.* n³ expresses input to layer 3
- Input weight matrix from layer k to layer l can be shown as IW^{l,k}, also for layer weight matrix, *i.e.LW^{l,k}*



Figure: Example of a perceptron

Matlab Notation Considerations

- superscripts \Leftrightarrow cell array indices, *e.g.* $p^1 \rightarrow p\{1\}$
- subscripts \Leftrightarrow indices within parentheses, *e.g.* $p_2 \rightarrow p(2)$
- \Rightarrow superscripts + subscripts ,*e.g.* $p_2^1 \rightarrow p\{1\}(2)$
- indices within parentheses \Leftrightarrow a second cell array index¹ *e.g.* $p^{1}(k-1) \rightarrow p\{1, k-1\}$

¹also in the Matlab help, it should be corrected; $p\{1, k-1\} \rightarrow p\{1, k-1\} = 0$

- It breaks into two parts, supervised and unsupervised learning, we consider the first topic
- The objective is to reduce the error e, which is the difference t-a between the neuron response a and the target vector t
- There are many algorithms that do this and we will introduce them
- All the algorithms compute Δw utilizing some methods

Learning Alghorithms

Hebb weight learning rule²

$$\Delta w^k = ca^k p^k$$

MATLAB command learnh

Perceptron weight and bias learning function

$$\Delta w^k = e^k (p^k)^T$$

MATLAB command learnp

Normalized perceptron weight and bias learning function

$$pn = rac{p}{\sqrt{1 + \|p\|^2}}, \quad \Delta w^k = e^k (pn^k)^T$$

MATLAB command learnpn

²in all, **e**: error, **p**: input and **a**: output

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Learning Alghorithms

Widrow-Hoff weight/bias learning function

$$\Delta w^k = c e^k (p n^k)^T$$

learning rate c, MATLAB command learnwh Training is using the learning rule to update the weights of network repeatedly

$$w_{new}^k = w_{old}^k + \Delta w^k$$

MATLAB command train

Utility Functions

- MATLAB command init, Initialize neural network
- MATLAB command sim, Simulate neural networks
- MATLAB command adapt
 Allow neural network to change weights and biases on inputs
- MATLAB command newp, create perceptron

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Perceptron problem, step by step

- Creating a Perceptron, >> net=newp(P,T);
- Assigning initial weight and bias,
 - >> net.IW{1,1}= [**w1 w2**];
 - >> net.b{1} = [b];
- Determining number of pass,

>> net.trainParam.epochs = pass;

- Training Network, >> net = train(net,p,t);
- Test and Verifying, >> a = sim(net,p);

Perceptron problem, step by step

Example 1: Classifying displayed data



Solve Problem

Perceptron problem, step by step

Example 1; Solution

```
% number of samples of each class
N = 20;
% define inputs and outputs
offset = 5; % offset for second class
x = [randn(2,N) randn(2,N)+offset]; % inputs
v = [zeros(1,N) ones(1,N)]; % outputs
% Plot input samples with PLOTPV (Plot perceptron
input/target vectors)
plotpv(x,y);
net=newp(x,y);
net = train(net,x,y); % train network
figure(1)
plotpc(net.IW{1}, net.b{1});
```

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Solve Problem

Perceptron problem, step by step

Example 1; Solution



Note

- net.trainParam.epochs
- net.trainParam.goal

Random Weights Initialization

```
net.inputweights{1,1}.initFcn = 'rands';
net.biases{1}.initFcn = 'rands';
net = init(net);
```

Example 2: Classifying displayed data



Example 2; Solution

```
K = 30;
% define classes
q = .6; % offset of classes
A = [rand(1, K) - q; rand(1, K) + q]; B = [rand(1, K) + q;
rand(1, K) + q];
C = [rand(1,K)+q; rand(1,K)-q]; D = [rand(1,K)-q;
rand(1, K) - q];
% plot classes
plot(A(1,:),A(2,:),'bs')
hold on; grid on
plot(B(1,:),B(2,:),'r+'); plot(C(1,:),C(2,:),'go');
plot(D(1,:),D(2,:),'m*');
% text labels for classes
text(.5-q,.5+2*q,'Class A'); text(.5+q,.5+2*q,'Class B')
```

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Example 2; Solution-Cont'd

```
text(.5+q,.5-2*q,'Class C'); text(.5-q,.5-2*q,'Class D')
a = [0 \ 1]'; b = [1 \ 1]';
c = [1 \ 0]'; d = [0 \ 0]';
P = [A B C D];
% define targets
T = [repmat(a, 1, length(A)) repmat(b, 1, length(B)) \dots
repmat(c,1,length(C)) repmat(d,1,length(D)) ];
net=newp(P,T);
E = 1;
net.adaptParam.passes = 1;
linehandle = plotpc(net.IW{1},net.b{1}); n = 0;
while (sse(E) & n<1000)
n = n+1;
[net, Y, E] = adapt(net, P, T);
linehandle = plotpc(net.IW{1}, net.b{1}, linehandle);
drawnow;
end
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```

Example 2; Solution- Cont'd





Thank You

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