

# Signals and Systems

## Lecture 1: Signals and Systems

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## What are Signals and Systems?

### Signal

Signal Energy and Power

Transformations of Independent Variable

Signal Properties

Complex Exponential Signals

### Systems

System Properties



# What are Signals and Systems?

- ▶ **Signal:** a function of one or several independent variables which conveys behavioral information of an event
  - ▶ Give me some examples :)
- ▶ **System:** It receives signals, processes them and produces novel signals



- ▶ Give me some examples :)

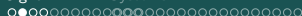
# Signal

- ▶ In this course we consider signals with **one** independent variable.
- ▶ A signal can be
  - ▶ **Deterministic**: It can be described by a math relation or a table. (Give me an example)
  - ▶ **Stochastic**: It cannot be described by determined math relation. It may be defined by probability density function, distribution function or etc. (Give me an example)
- ▶ A signal also can be
  - ▶ **Continuous Time ( $x(t)$ )**: The independent variable (time) is continuous. (Example!)
  - ▶ **Discrete Time ( $x[n]$ )**: The independent variable (time) is discrete. (Example!)
    - ▶ **Digital**: Both independent variable and signal domain are discrete.



# Signal Energy and Power

- ▶ Usually the signals represent physical quantities  $\rightsquigarrow$  it captures power and energy
- ▶ Consider voltage ( $v(t)$ ) and current ( $i(t)$ ) across a resistor ( $R$ ).
- ▶ The instantaneous power is:  $p(t) = v(t)i(t) = \frac{1}{R}v^2(t)$
- ▶ Total energy over time interval  $[t_1, t_2]$ :  $\int_{t_1}^{t_2} p(t)dt = \int_{t_1}^{t_2} \frac{1}{R}v^2(t)dt$
- ▶ Average power over time interval  $[t_1, t_2]$ :  
$$\frac{1}{t_2-t_1} \int_{t_1}^{t_2} p(t)dt = \frac{1}{t_2-t_1} \int_{t_1}^{t_2} \frac{1}{R}v^2(t)dt$$



# Signal Energy and Power

- ▶ In general signals may take on complex values.
- ▶ General definition of total energy over time interval  $[t_1, t_2]$ / $[n_1, n_2]$ :

$$\int_{t_1}^{t_2} |x(t)|^2 dt \quad \sum_{n_1}^{n_2} |x[n]|^2$$

- ▶ General definition of average power over time interval  $[t_1, t_2]$ / $[n_1, n_2]$ :

$$\frac{1}{t_2 - t_1} \int_{t_1}^{t_2} |x(t)|^2 dt \quad \frac{1}{n_2 - n_1 + 1} \sum_{n_1}^{n_2} |x[n]|^2$$

# Signal Energy and Power

- ▶ General definition of total energy over time interval  $[-\infty, \infty]/[-\infty, \infty]$ :

$$E_{\infty} = \lim_{T \rightarrow \infty} \int_{-T}^T |x(t)|^2 dt \qquad \lim_{N \rightarrow \infty} \sum_{-N}^N |x[n]|^2$$

- ▶ General definition of average power over time interval  $[-\infty, \infty]/[-\infty, \infty]$ :

$$P_{\infty} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt \qquad \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{-N}^N |x[n]|^2$$



# Signal Energy and Power

- ▶ Based on signal energy and power, a signal may have:
  - ▶ Finite energy, zero average power
  - ▶ Finite average power, infinite energy
  - ▶ Both  $P_\infty$  and  $E_\infty$  are infinite

# Signal Energy and Power

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    - ▶ Example:  $x = \begin{cases} 4 & 0 \leq t \leq 1 \\ 0 & \text{otherwise} \end{cases} \rightsquigarrow E_{\infty} = 16, P_{\infty} = 0$
  - ▶ Finite average power, infinite energy
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# Signal Energy and Power

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- ▶ Both  $P_{\infty}$  and  $E_{\infty}$  are infinite

- ▶ Example:  $x(t) = 5t^2$

## Transformations of Independent Variable (time axis)

### ► Time Shift ( $x(t \pm t_0)$ / $x[n \pm n_0]$ )

$t_0$  and  $n_0$  are positive.

1.  $x(t - t_0)$ / $x[n - n_0]$

- It is a delayed version of  $x(t)$ / $x[n]$
- Shift the signal to the right by  $t_0$ / $n_0$

2.  $x(t + t_0)$ / $x[n + n_0]$

- It is an advanced version of  $x(t)$ / $x[n]$
- Shift the signal to the left by  $t_0$ / $n_0$

# Transformations of Independent Variable (time axis)

- ▶ **Time Reversal** ( $x(-t)$  /  $x[-n]$ )
  - ▶ Reflects the signal about  $t = 0$  /  $n = 0$
- ▶ **Time Scaling** ( $x(at)$  /  $x[an]$ )
  1.  $|a| > 1$ 
    - ▶ It is compressed
  2.  $|a| < 1$ 
    - ▶ It is stretched
    - ▶ For discrete signal,  $n/a$  should be an integer

# Transformations of Independent Variable (time axis)

- ▶ In general form ( $x(\alpha t + \beta)$  /  $x[\alpha n + \beta]$ )
  1. Shift the signal by  $\beta$ 
    - ▶  $\beta > 0$ : shift to left
    - ▶  $\beta < 0$ : shift to right
  2. Scale or reverse the signal by  $\alpha$ 
    - ▶  $|\alpha| > 1$ : compress
    - ▶  $|\alpha| < 1$  stretch
    - ▶  $\alpha < 0$  reverse

# Signal Properties

## ▶ Periodic Signals

- ▶  $\exists T > 0$  s.t.  $x(t) = x(t + T)$
- ▶  $\exists N > 0$  & *integer* s.t.  $x[n] = x[n + N]$
- ▶ The fundamental period ( $T_0/N_0$ ) is the smallest positive value of  $T/N$  which the above equality holds
- ▶ Is a constant signal periodic?
- ▶ If a signal is not periodic it is called *aperiodic*



# Signal Properties

## ► Even and Odd signals

- **Even Signal:** It is identical to its time-reversed (its reflection about the origin)

$$x(-t) = x(t)$$

$$x[-n] = x[n]$$

- **Odd Signal:** It is symmetric about the origin

$$x(-t) = -x(t)$$

$$x[-n] = -x[n]$$

It should be 0 at ( $t=0/n=0$ )

- Any signal can be broken to sum of an odd and an even signal:
  - Even part:  $E\{x(t)\} = \frac{1}{2}[x(t) + x(-t)]$
  - Odd part:  $O\{x(t)\} = \frac{1}{2}[x(t) - x(-t)]$

# Continuous-Time Complex Exponential Signals

$$x(t) = Ce^{at}$$

- ▶ Based on  $C$  and  $a$  the signal has different behavior
  1.  $C$  and  $a$  are real
    - ▶  $a > 0$   $\rightsquigarrow$  growing signal
    - ▶  $a < 0$   $\rightsquigarrow$  decaying signal
    - ▶  $a = 0$   $\rightsquigarrow$  constant signal

## 2. $C$ is real and $a$ is purely imaginary ( $x(t) = e^{j\omega_0 t}$ )

- ▶ It is periodic:

$$e^{j\omega_0 t} = e^{j\omega_0(t+T)} = e^{j\omega_0 t} e^{j\omega_0 T} \rightsquigarrow e^{j\omega_0 T} = 1$$

- ▶ If  $\omega_0 = 0 \rightsquigarrow$  It is periodic for any value of  $T$
- ▶ If  $\omega_0 \neq 0 \rightsquigarrow \omega_0 T = 2\pi \rightsquigarrow T_0 = \frac{2\pi}{|\omega_0|}$
- ▶  $e^{j\omega_0 t}$  and  $e^{-j\omega_0 t}$  have the same fundamental period.



► **Cosinusoidal signal**  $x(t) = A\text{Cos}(w_0t + \phi)$

- Sinusoidal signals and exponential signals can be used for expressing physical systems which conserve energy. Example?
- It is periodic:  $T_0 = \frac{2\pi}{w_0}$ , ( $T_0$ : Fundamental period;  $w_0$  : Fundamental frequency)
- Complex exponential signal can be written in terms of sinusoidal signals with same fundamental period:(Use Euler's relation)

$$e^{jw_0t} = \text{Cos}w_0t + j\text{sin}w_0t$$

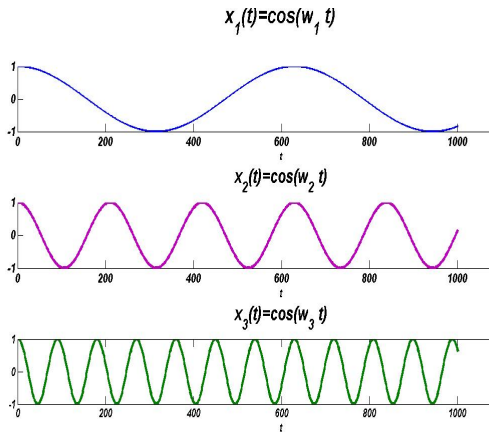
- Sinusoidal signals can be expressed by complex exponential signals with same fundamental period:

$$A\text{Cos}(w_0t + \phi) = \frac{A}{2}e^{j\phi}e^{jw_0t} + \frac{A}{2}e^{-j\phi}e^{-jw_0t} = A\Re\{e^{j(w_0t+\phi)}\}$$

$$A\text{Sin}(w_0t + \phi) = A\Im\{e^{j(w_0t+\phi)}\}$$

# Cosinusoidal Signals/ Exponential Signals

- In continuous-time (CT) Cosinusoidal (sinusoidal) signals:  $\omega_0 \uparrow \Rightarrow T_0 \downarrow$   
 $\omega_1 < \omega_2 < \omega_3$



# Cosinusoidal Signals/ Exponential Signals

- ▶ They have finite average power and infinite total energy:
  - ▶ In one period:  $E_{period} = \int_0^{T_0} |e^{j\omega_0 t}|^2 dt = T_0$ ,  $P_{period} = \frac{1}{T_0} E_{period} = 1$
  - ▶ By repeating  $T_0$  infinite time:  $E_\infty$  becomes infinite,  $P_\infty = 1$
- ▶ They can be applied in making a set of harmonically related complex exponentials with common period  $T_0$ 
  - ▶  $\phi_k(t) = e^{jk\omega_0 t}$ ,  $k = 0, \pm 1, \pm 2, \dots$
  - ▶  $e^{j\omega t}$  is periodic with period  $T_0$ :  
 $e^{j\omega T_0} = 1 \rightsquigarrow \omega T_0 = 2\pi k$ ,  $\omega_0 = \frac{2\pi}{T_0}$ ,  $k = 0, \pm 1, \pm 2, \dots$
  - ▶ The  $k$ th harmonic is periodic with fundamental freq.  $|k|\omega_0$

# Time Shift $\Leftrightarrow$ Change Phase

- Time Shift:  $A\cos(\omega_0(t + t_0) + \phi) = A\cos(\omega_0 t + \underbrace{\omega_0 t_0}_{\phi_0} + \phi)$  Change phase

# Time Shift $\Leftrightarrow$ Change Phase

- ▶ Time Shift:  $A\cos(\omega_0(t + t_0) + \phi) = A\cos(\omega_0 t + \underbrace{\omega_0 t_0}_{\phi_0} + \phi)$  Change phase
- ▶ Change phase:  $A\cos(\omega_0 t + \phi + \phi_0) = A\cos(\omega_0 t + \omega_0 t_0 + \phi)$  Time Shift



# Time Shift $\Leftrightarrow$ Change Phase

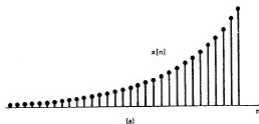
- ▶ Time Shift:  $A\cos(\omega_0(t + t_0) + \phi) = A\cos(\omega_0 t + \underbrace{\omega_0 t_0}_{\phi_0} + \phi)$  Change phase
- ▶ Change phase:  $A\cos(\omega_0 t + \phi + \phi_0) = A\cos(\omega_0 t + \omega_0 t_0 + \phi)$  Time Shift
- ▶  $\cos(\omega_0 t)$  is an Even signal  $\rightarrow \cos(\omega_0 t - \frac{\pi}{2}) = \sin(\omega_0 t)$  is an Odd Signal



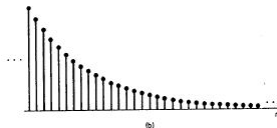
# Discontinuous-Time (DT) Complex Exponential Signals $x[n] = Ca^n = Ce^{\beta n}$

## 1. $a$ and $C$ are real

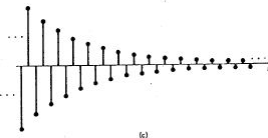
▶  $a > 1$ :



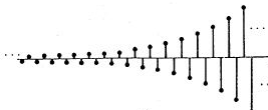
▶  $0 < a < 1$ :



▶  $-1 < a < 0$ :



▶  $a < -1$ :



2.  $C$  is real and  $a$  is purely imaginary ( $x[n] = e^{j\omega_0 n}$ )

- ▶ Similar to CT exponential signals it is related to Cosinusoidal signals:

$$x[n] = A \cos(\omega_0 n + \phi)$$

- ▶ By using Euler's relation:  $e^{j\omega_0 n} = \cos \omega_0 n + j \sin \omega_0 n$

$$A \cos(\omega_0 n + \phi) = \frac{A}{2} e^{j\phi} e^{j\omega_0 n} + \frac{A}{2} e^{-j\phi} e^{-j\omega_0 n}$$

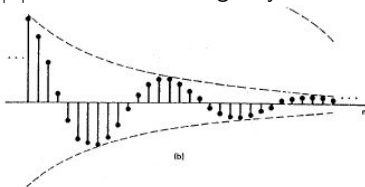
- ▶ Similar to CT exponential signals its average power is finite (1) and its total energy is infinite

### 3. Both $C$ and $a$ are complex

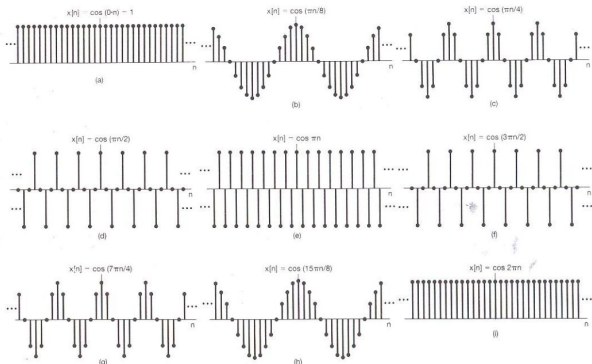
- ▶ where  $C = |C|e^{j\theta}$ ,  $a = |a|e^{jw_0} \rightsquigarrow Ca^n = |C||a|^n e^{j(w_0n+\theta)} = |C||a|^n (\text{Cos}(w_0n + \theta) + j\text{Sin}(w_0n + \theta))$ 
  - ▶  $|a| = 1$ : both real and imaginary terms are sinusoidal
  - ▶  $|a| > 1$ : real and imaginary terms are increasing



- ▶  $|a| < 1$ : real and imaginary terms are decreasing



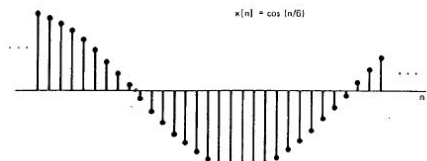
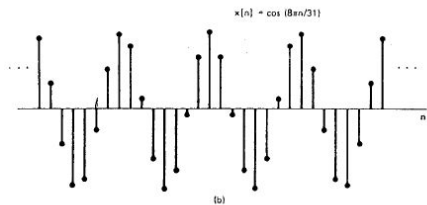
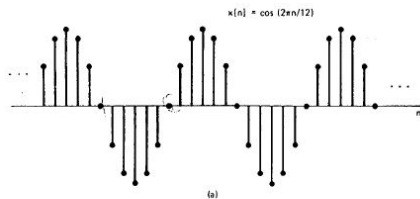
- ▶  $w_0 \uparrow$ :
  - ▶  $0 < w_0 < \pi \rightsquigarrow$  rate of oscillation  $\uparrow$
  - ▶  $\pi < w_0 < 2\pi \rightsquigarrow$  rate of osc.  $\downarrow$
- ▶  $w_0 = \pi$  has highest rate of osc.  
( $e^{j\pi n} = (-1)^n$ )
- ▶ Rate of osc. for  $w_0 = 0$  equals to  $w_0 = 2\pi$



- ▶ To have periodic DT exponential signal:  $e^{jw_0 n} = e^{jw_0(n+N)}$
- ▶  $e^{jw_0 N} = 1 \rightsquigarrow Nw_0 = 2\pi m$
- ▶  $m, N$  should be an integer
- ▶ Fundamental period  $N = \frac{2\pi m}{w_0}$



- ▶  $x[n] = \text{Cos}\left(\frac{2\pi n}{12}\right)$  and  $x(t) = \text{Cos}\left(\frac{2\pi t}{12}\right)$  are periodic ( $T_0 = N = 12$ )
- ▶  $x(t) = \text{Cos}\left(\frac{8\pi t}{31}\right)$  is periodic ( $T_0 = \frac{31}{4}$ )
- ▶  $x[n] = \text{Cos}\left(\frac{8\pi n}{31}\right)$  is periodic ( $N = 31$ )
- ▶  $x(t) = \text{Cos}\left(\frac{t}{6}\right)$  is periodic ( $T_0 = \frac{12}{\pi}$ )
- ▶ **But**  $x[n] = \text{Cos}\left(\frac{n}{6}\right)$  is not periodic!
- ▶  $N = 12\pi m$ : no integer  $m$  can be found to make  $N$  an integer





# Time Shift $\Rightarrow$ Change Phase

- Time Shift:  $A\cos(\omega_0(n + n_0) + \phi) = A\cos(\omega_0 n + \underbrace{\omega_0 n_0}_{\phi_0} + \phi)$  Change phase

# Time Shift $\Rightarrow$ Change Phase

- ▶ Time Shift:  $ACos(\omega_0(n + n_0) + \phi) = ACos(\omega_0 n + \underbrace{\omega_0 n_0}_{\phi_0} + \phi)$  Change phase
- ▶ Change phase:  $ACos(\omega_0 n + \phi + \phi_0) \stackrel{?}{=} ACos(\omega_0 n + \omega_0 n_0 + \phi)$  Not Always Time Shift

# Compare $e^{j\omega_0 t}$ in CT and DT

$e^{j\omega_0 t}$ in CT	$e^{j\omega_0 n}$ in DT
Distinct Signal for Distinct value of $\omega_0$ $\omega_1 \neq \omega_2 \rightsquigarrow A\cos(\omega_1 t) \neq A\cos(\omega_2 t)$	Identical Signals for exponentials at frequencies separated by $2\pi$ $\omega_1 \neq \omega_2$ If $\omega_2 = \omega_1 + 2\pi m$ $\rightsquigarrow A\cos(\omega_1 n) = A\cos(\omega_2 n)$
Periodic for any choice of $\omega_0$	Only periodic if $\omega_0 = \frac{2\pi m}{N}$ for some integers $N > 0, m$
Fundamental frequency $\omega_0$	Fundamental frequency $\frac{\omega_0}{m}$
Fundamental Period $\omega_0 = 0$ undefined $\omega_0 \neq 0$ $\frac{2\pi}{\omega_0}$	Fundamental Period $\omega_0 = 0$ undefined $\omega_0 \neq 0$ $m\left(\frac{2\pi}{\omega_0}\right)$

- ▶ Harmonically related complex exponentials with common period  $N$
- ▶ DT exponential signals can make harmonically related sets :  

$$\phi_k[n] = e^{jk(\frac{2\pi}{N})n}$$
- ▶ BUT we have only  $N$  different harmonic ( $k = 0, \dots, \pm(N - 1)$ )
  - ▶  $e^{j(k+N)(\frac{2\pi}{N})n} = e^{jk(\frac{2\pi}{N})n} e^{j2\pi n} = e^{jk(\frac{2\pi}{N})n}$
  - ▶  $\therefore \phi_N[n] = \phi_0[n], \dots \phi_{-1}[n] = \phi_{N-1}[n], \dots$

# Unit Step and Unit Impulse

- ▶ DT unit impulse:  $\delta[n] = \begin{cases} 0 & n \neq 0 \\ 1 & n = 0 \end{cases}$
- ▶ DT unit step:  $u[n] = \begin{cases} 0 & n < 0 \\ 1 & n \geq 0 \end{cases}$
- ▶ Unit impulse can be defined based on unit step:  $\delta[n] = u[n] - u[n - 1]$
- ▶ Unit step can be described based on unit impulse:  $u[n] = \sum_{m=-\infty}^n \delta[m]$ 
  - ▶ One can also define it as:  $u[n] = \sum_{k=-\infty}^0 \delta[n - k] = \sum_{k=0}^{\infty} \delta[n - k]$
- ▶ Unit impulse has sampling property:  $x[n]\delta[n - n_0] = x[n_0]\delta[n - n_0]$

# Unit Step and Unit Impulse

- ▶ CT unit step:

$$u(t) = \begin{cases} 0 & t < 0 \\ 1 & t > 0 \end{cases}$$

- ▶ It is discontinuous  
(at  $t=0$ )

- ▶ Impulse Signal

$$\delta(t) = \frac{du(t)}{dt}$$

- ▶  $\delta(t) = \lim_{\Delta \rightarrow 0} \delta_{\Delta}(t)$

# Unit Step and Unit Impulse

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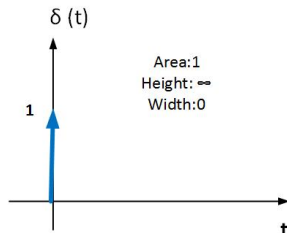
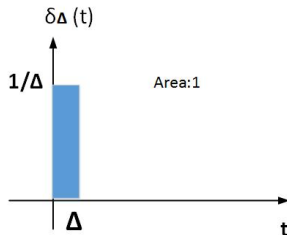
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# Unit Step and Unit Impulse

- ▶ Unit step can be described based on unite impulse:  $u(t) = \int_{-\infty}^t \delta(\tau) d\tau$ 
  - ▶ One can also define it as:  $u(t) = \int_{-\infty}^t \delta(\tau) d\tau = \int_0^{\infty} \delta(t - \sigma) d\sigma$
- ▶ Unite impulse has sampling property:  $x(t)\delta(t - t_0) = x(t_0)\delta(t - t_0)$

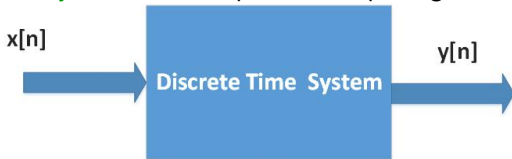


# Systems

- ▶ A system provides output signals by processing input signals
  - ▶ **Continuous-Time systems:** Both input and output signals are continuous.



- ▶ **Discrete-Time systems:** Both input and output signals are discrete.

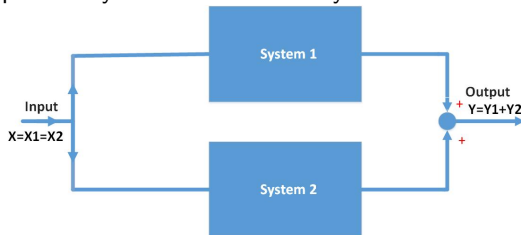


# Interconnection Systems

- ▶ Some systems consist of some interconnected subsystems:
  - ▶ **Series (Cascade) interconnection:** Output of first subsystem is input of the second subsystem; output of system is output of subsystem 2.

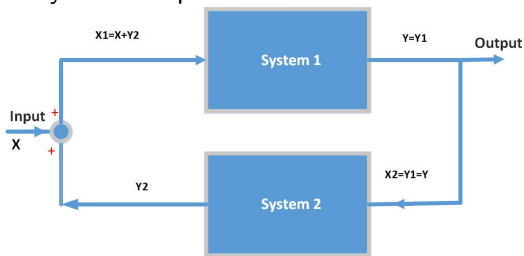


- ▶ **Parallel interconnection:** Both subsystems receive the same input signal and Output the system is sum of subsystem 1 and subsystem 2.



# Interconnection Systems

- **Feedback interconnection:** Output of subsystem 1 is be input of subsystem 2; output of subsystem 2 is fed back and added to external input to make subsystem 1 input.



# System Properties

- ▶ **System with/without memory:**
  - ▶ Output of a **memoryless** system for each value of the independent variable at a given time depends on the input at the same time. (Example?)
  - ▶ If output of a system at a given time depends on either future or past time input, it is called **system with memory**
    - ▶ In physical systems memory of a system is related to storing energy like a capacitor in electrical circuit.

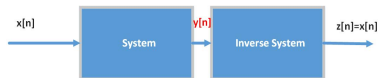
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## ▶ Invertibility

- ▶ In **invertible** system distinct inputs lead to distinct output.
- ▶ If an inverse exists, by cascading it with the original system, the resulting output equals to input of the first system



## ▶ Does cascading two invertible subsystem yield to invertible system?

# System Properties

## ► Causality

- Output of a **causal** system depends on the present and past time.
- They are called **nonpredictive** systems.
- All memoryless systems are causal

## ► Stability

- Different type of stability is defined for a system such as I/s stability, asymptotic stability and...
- In this course **Bounded Input Bounded Output (BIBO)** stability is considered:
  - small input does not make the output diverge.
  - A counterexample is enough to show a system is unstable.
  - To show the stability one should prove it through the stability definition.

## ► Time invariancy

- The characteristic of a **time invariant** system does not change over time:
  - If  $x(t) \rightarrow y(t) \Rightarrow x(t - t_0) \rightarrow y(t - t_0)$
  - If  $x[n] \rightarrow y[n] \Rightarrow x[n - n_0] \rightarrow y[n - n_0]$
- If time is explicitly mentioned in system model it is called **time varying**

# System Properties

## ▶ Linearity

▶ For **linear** system superposition property is hold:

▶ Additivity property:  $x_1 + x_2 \Rightarrow y_1 + y_2$

▶ scaling(homogeneity) property: for a complex  $a$ ,  $ax \Rightarrow ay$

▶ For linear systems  $x(t) = 0(x[n] = 0) \rightsquigarrow y(t) = 0(y[n] = 0)$

▶ **Incrementally linear system** consists of a linear system adding with a



zero-input response.

▶ The difference between the responses to any two inputs will be a linear function of the difference between two inputs

▶ **Example:**  $y(t) = 5x(t) + 6$