

Computational Intelligence Introduction

Farzaneh Abdollahi

Department of Electrical Engineering

Amirkabir University of Technology

Fall 2010

A (10) < A (10) </p>

Fuzzy Systems

What are Fuzzy Systems? A Brief History Fuzzy Applications

Neural Networks

Biological Neural Networks Artificial Neural Networks Neural Network Applications

Reference Books

Topics





- Computational Intelligence provides us the opportunity to find a solution for the problems which were merely solvable by human intelligence.
- Computational intelligence machine can learn, remember, and justify similar to human

What are Fuzzy Systems?

Fuzzy Systems

- As a word, fuzzy is defined as "blurred, indistinct; imprecisely defined; confused, vague." !!!
- The fuzzy systems is defined based on precise theory and applies to describe complex system which cannot be defined simply by precise models.
- The justification for fuzzy systems theory:
 - 1. The real world is too complicated for precise descriptions to be obtained, → approximation (or fuzziness) must be introduced to obtain a reasonable, yet trackable model.
 - 2. As we move into the information era, human knowledge becomes increasingly important. We need a theory to formulate human knowledge in a systematic manner and put it into engineering systems, together with other information like mathematical models and sensory measurements.



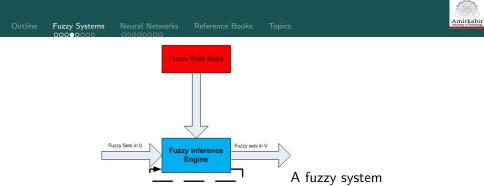
What are Fuzzy Systems?

- A good engineering theory should make use of all available information effectively.
- ► For many practical systems, important information comes from:
 - 1. Human experts who describe their knowledge about the system in natural languages
 - 2. Sensory measurements and mathematical models that are derived according to physical laws.
- An important task: combining these two types of information into system designs.
- Fuzzy Systems transform a human knowledge base into a mathematical formula



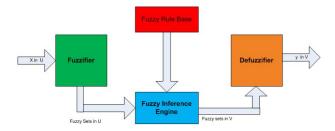
What are Fuzzy Systems?

- To construct a fuzzy system:
 - 1. Obtain a collection of fuzzy IF-THEN rules from human experts or based on domain knowledge.
 - 2. Combine these rules into a single system.
- Example: For designing a controller to automatically control the speed of a car based on a driver knowledge the rules are
 - ► IF speed is low, THEN apply more force to the accelerator
 - ► IF speed is medium, THEN apply normal force to the accelerator
 - ► IF speed is high, THEN apply less force to the accelerator



- fuzzy rule base consists of the rules
- fuzzy inference engine combines the fuzzy IF-THEN rules into a mapping from fuzzy sets in the input space to fuzzy sets in the output space based on fuzzy logic principles.
 - ► If the dashed feedback line exists, the system becomes the named fuzzy dynamic system.
 - The main problem: (the inputs and outputs are fuzzy sets (words in natural languages), but in engineering systems the inputs and outputs are real-valued variables.





- ► Fuzzifier transforms a real-valued variable into a fuzzy set at input
- ► Defuzzifier transforms a fuzzy set into a real-valued variable at output.



- Fuzzy theory was initiated by Lotfi A. Zadeh in 1965 with his seminal paper "Fuzzy Sets" [1].
 - he wrote that to handle biological systems " we need a radically different kind of mathematics, the mathematics of fuzzy or cloudy quantities which are not describable in terms of probability distributions"
- ► The fuzzy controllers was born for real systems, in 1975, by Mamdani and Assilian [2].
- In early 80's Japanese engineers found the fuzzy controllers very user friendly.





- Fuzzy theory was initiated by Lotfi A. Zadeh in 1965 with his seminal paper "Fuzzy Sets" [1].
- ► The fuzzy controllers was born for real systems, in 1975, by Mamdani and Assilian [2].
 - They designed a fuzzy controller to control a steam engine.
- In early 80's Japanese engineers found the fuzzy controllers very user friendly.





- Fuzzy theory was initiated by Lotfi A. Zadeh in 1965 with his seminal paper "Fuzzy Sets" [1].
- ► The fuzzy controllers was born for real systems, in 1975, by Mamdani and Assilian [2].
- In early 80's Japanese engineers found the fuzzy controllers very user friendly.
 - It does not require a mathematical model of the process
 - In 1980, Sugeno began to create "Japan's first fuzzy application-control of a Fuji Electric water purification plarit [3].
 - He was pioneer designing on a fuzzy robot, a self-parking car.





- ► When is it appropriate to use fuzzy logic?
 - A mathematical model of the process does not exit or too complex or expensive to be evaluated fast in real time
 - There are high ambient of noise
 - When the process involves human interaction and an expert can specify some rules underlying the system behavior

Some Fuzzy Applications

- 1. Pattern recognition
 - image, audio, signal processing
- 2. Quantitative analysis
 - operation research, management
- 3. Inference
 - expert systems for digenesis, planning, prediction, software engineering in medicine, business, and etc
- 4. Control (the most popular)
 - modeling and identification of nonlinear systems, observation and control

(4 同) トイヨト イヨト

Fuzzy Systems

- Fuzzy Washing Machines at Matsushita Electric Industrial Company in Japan(1990)
 - ➤ a fuzzy system automatically set the proper cycle (output) according to kind and amount of dirt and the size of the load (3 inputs).
- ► Digital Image Stabilizer in camcorder
- Fuzzy Car at Mitsubishi (1992)
- ► Fuzzy Control of Subway Train at Sendai in Japan

Fuzzy Systems

- Fuzzy Washing Machines at Matsushita Electric Industrial Company in Japan(1990)
- ► Digital Image Stabilizer in camcorder based on simple rules:
 - IF all the points in the picture are moving in the same direction, THEN the hand is shaking
 - IF only some points in the picture are moving, THEN the hand is not shaking
- Fuzzy Car at Mitsubishi (1992)
- ► Fuzzy Control of Subway Train at Sendai in Japan

Fuzzy Systems

- Fuzzy Washing Machines at Matsushita Electric Industrial Company in Japan(1990)
- Digital Image Stabilizer in camcorder
- ► Fuzzy Car at Mitsubishi (1992) controls:
 - car's automatic transmission (downshifts on curves and also keeps the car from upshifting inappropriately)
 - suspension (register vibration and height changes in the road and adjusts the suspension for a smoother ride)
 - traction (prevents excess speed on corners and improves the grip on slick roads by deciding whether they are level or sloped)
 - four-wheel steering (adjusts the response angle of the rear wheels according to road conditions and the car's speed)
 - air conditioner (monitors sunlight, temperature, and humidity to enhance the environment inside the car).
- ► Fuzzy Control of Subway Train at Sendai in Japan

イロト イポト イヨト イヨト

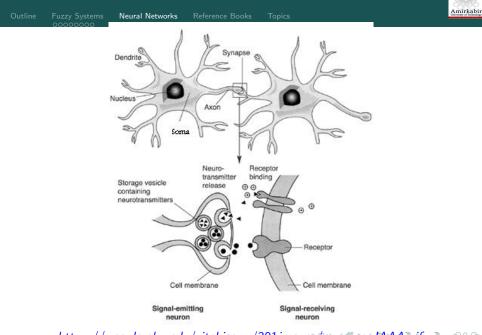
Fuzzy Systems

- Fuzzy Washing Machines at Matsushita Electric Industrial Company in Japan(1990)
- Digital Image Stabilizer in camcorder
- Fuzzy Car at Mitsubishi (1992)
- ► Fuzzy Control of Subway Train at Sendai in Japan The fuzzy control:
 - The constant speed controller (it starts the train and keeps the speed below the safety limit),
 - the automatic stopping controller (it regulates the train speed in order to stop at the target position).



Biological Neural Networks

- Although the processor elements of a computer (semi-conductors) act much faster than processor elements of human brain (neurons), human response is faster than a computer.
 - In human brain, neurons work in parallel and are tightly connected together
 - In computer the calculations are doing sequential.
- Artificial neural networks mimic brain capability of calculations and decision making.
- ► The simplest unit of neural networks named *neurons*
- Neurons transfer the information from sense organs to brain and from brain to moving organs
- Each neuron is connected to other neurons and they totally make the neural network system.
- ► There are more than 100 billion neurons in human body which most of them are located in brain.



http://people.eku.edu/ritchisong/301images∮synapsen/IAAA.gif Farzaneh Abdollahi Neural Networks 13/21





► A biological brain includes three main parts:

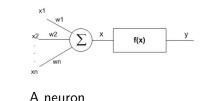
- **Dendrites:** Receive signals from other neurons.
 - The neurotransmitter chemicals are released to transmitted the signals through synaptic gaps
- Soma or body of the cell which accumulates all input signals.
- ► When the input signals reach an action potential threshold, they are transmitted to other neurons through Axon
- Each neuron can adapt itself with environment changes
- The neural network structure is changing based on reinforcement and weakening the synaptic connections.
- Learning is obtained by changing the synaptic gaps.



Artificial Neural Networks

Neural Networks

- ► Artificial neural networks is inspired by biological neural networks.
- ► So the structure of artificial neural networks are based on:
 - ► Simple elements named neurons where information is processed.
 - ► Signals are transformed through the connections between neurons.
 - To each connection a *weight* is assigned which is multiplied to the transferring signal.
 - ► At each neuron there is an *activation function* which is normally a nonlinear function. This function provides the output of the neuron.



►
$$x = w_1 x_1 + w_2 x_2 + ... + w_n x_n$$
, $X = W x$, $y = W x_1 + w_2 x_2 + ... + w_n x_n$



- ▶ Each artificial neural network (NN) is distinguished by
 - Pattern of connection between neurons (Neural network structure)
 - Method of defining weights (Learning)
 - Activation function
- By adjusting the weights, (synaptic gaps in biological neurons) the neural network learn a pattern.
- How much the artificial neural networks are similar to the biological neural networks?
 - It varies in different type of artificial neural networks based on its application.
 - ► For some researchers such as engineers high performance of the network in calculations and function approximation is more important.
 - In some research areas like neurology, emulating the biological behavior is more attractive.



In general the artificial NNs and biological neural networks are similar in

- 1. The processing elements (neurons) receive signals
- 2. Signals can be modified by weights (synaptic gaps)
- 3. Processing elements gather the weighed inputs
- 4. Under specified condition, the neuron provides output signal
- 5. Output of a neuron can be transferred to other neurons
- 6. The power of each synapse (weights) varies in different experience.

Neural Networks (NNs) capabilities

- Learning
- Parallel Processing
- Generalization
 - When a NN is trained, it can generalized its knowledge to the inputs which has not seen before
 - For example if a NN is used for recognizing letters, if it receive a noisy input, it still can recognize it and deliver the letter without noise.
- Fault toleration
 - NN can tolerate its malfunctioning in some circumstances.
 - Human is born with 100 billion neurons which some of them die but learning does not stop!!
 - Artificial NN should behave the same. Neural Networks



Neural Network Applications

Neural Networks

- 1. Signal Processing
 - Such as eliminating echo on telephone lines
- 2. Control (NN can be applied for nonlinear systems)
 - Identification, unmodeled dynamics, variable parameters
 - Observation
 - Control of nonlinear system
- 3. Pattern Recognition
 - Handwriting
 - Finger print
- 4. Medical
 - Help in diagnosing diseases based on symptoms
- 5. Speech Recognition
 - In classic methods, some rules are defined for standard pronunciation of letters and a look-up table for exceptions.
 - In NN, there is no need to extract the rules and exceptions. NN is trained based on I/O data.

Structure of NN

- Single layer
- Multiple layer
 - Feedforward
 - Feedback (Recurrent)

Training NN

- Supervised
- Unsupervised

Activation Function

- Linear
- ► Sigmoid, ...





Reference Books

► Text Books:

- 1. A Course in Fuzzy Systems and Control, L. X. Wang, Prentice-Hall International, Inc,1997
- 2. Fundamentals of Neural Networks Architectures, Algorithms and Applications, L. Faussett, , Prentice-Hall, 1994

► Other Reference Books:

- 1. Fuzzy Logic with Engineering Applications, T. J. Ross, John Wiley and Sons, 2nd edition 2004
- 2. Introduction to Artificial Neural Systems, J. K. Zurada, West publishing company, 2nd edition 2006
- 3. Neural networks and learning machines, S. S. Haykin, Prentice Hall , third edition,2008
- 4. Fundamentals of Neural Networks, M. B. Menhaj, Amirkabir University of Technology, 2009 (in Farsi)
- Fuzzy Computations, M. B. Menhaj, 2nd edition, Danesh Negar, 1388 (in Farsi)

イロト イポト イヨト イヨト



Topics

| Торіс | Date | Refs |
|---|------------|-----------|
| Introduction to Fuzzy Systems | Week 1 | Chap. 1 |
| Fuzzy Sets and Fuzzy Relations | Weeks 2,3 | Chap. 2-4 |
| Linguistic Variables and Fuzzy Rules | Week 4 | Chap. 5 |
| Fuzzy Systems(Inference Engine, | Weeks 5,6 | Chap. 7,8 |
| Fuzzifier, Defuzzifier,, Nonlinear Mapping) | | |
| Design of Fuzzy Systems | Week 7 | Chap. 13 |
| Introduction to Neural Networks | Week 8 | |
| Feed-forward Networks | Week 9,10 | |
| Radial Bases Functions | Week 11 | |
| Associative Memories | Week 12,13 | |
| Applications of Comp. Intelligence | Week 14,15 | |

イロト イヨト イヨト イヨト



L. A. Zadeh, "Fuzzy sets," *Informat. Control*, vol. 8, , pp. 338–353, 1965.

E. H. Mamdani and S. Assilian, "An experiment in linguistic synthesis with a fuzzy logic controlle," *Internationa Journal of Man Machin Studies*, vol. 7, no. 1, pp. 1–13, 1975.

Topics

T. Takagi and M. Sugeno, "Fuzzy identification of systems and its applications to modeling and control," *IEEE Trans. on Systems, Man, and Cybern.*, vol. 15, no 1, pp. 116–132, 1983.